

3. ADVANCED TOPICS ON SPACE-GROUP SYMMETRY

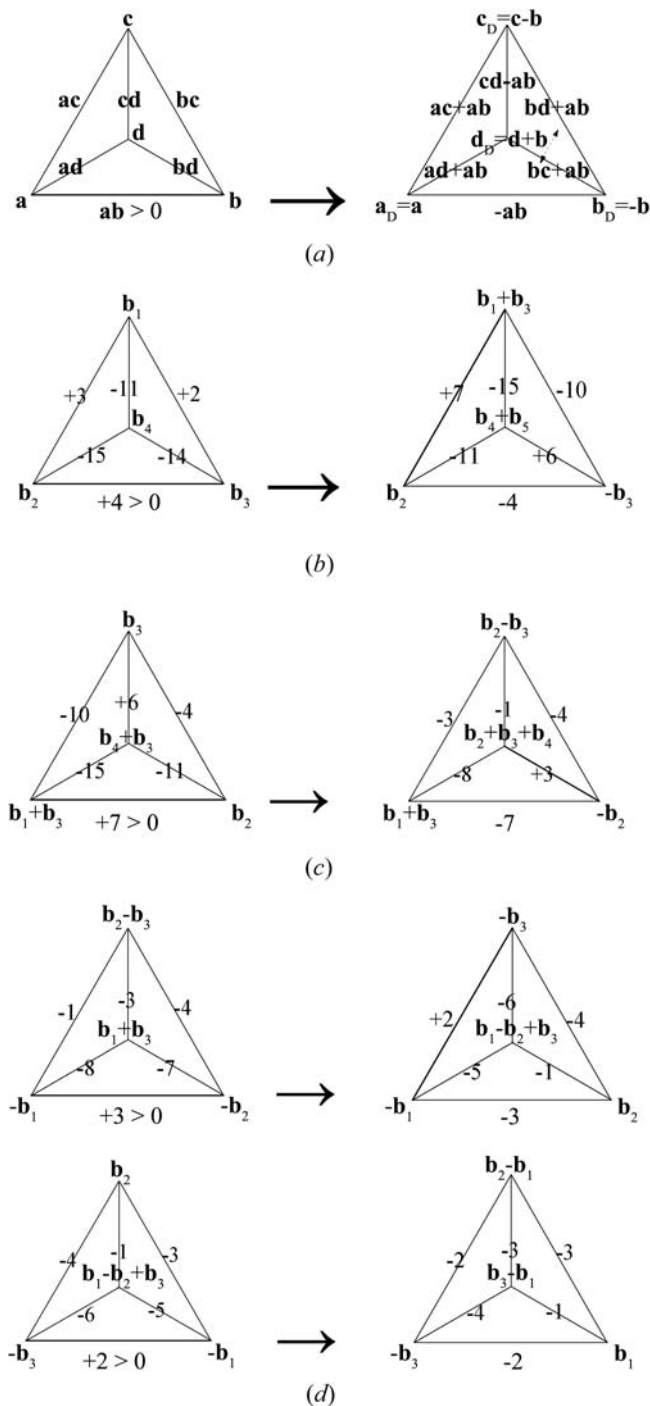


Figure 3.1.2.2
Delaunay reduction of Gruber's example (cf. Section 3.1.2.4). The edges of Selling tetrahedra are labelled by the scalar products of the vectors which designate the corners of the tetrahedra.

Table 3.1.2.4
Delaunay reduction for Gruber's example

a	b	c	d	ab, a _D b _D	ac, a _D c _D	ad, a _D d _D	bc, b _D c _D	bd, b _D d _D	cd, c _D d _D	a _D	b _D	c _D	d _D
b₂	b₃	b₁	b₄	+4 -4	+3 +7	-15 -11	+2 -10	14 +6	-11 -15	b₂	-b₃	b₁ + b₃	b₄ + b₃
b₁ + b₃	b₂	-b₃	b₃ + b₄	+7 -7	-10 -3	-15 -8	-4 -4	-11 +3	+6 -1	b₁ + b₃	-b₂	b₂ - b₃	b₂ + b₃ + b₄
-b₁	-b₂	b₂ - b₃	b₁ + b₃	+3 -3	-1 +2	-8 -5	-4 -4	-7 -1	-3 -6	-b₁	b₂	-b₃	b₁ - b₂ + b₃
-b₃	-b₁	b₂	b₁ - b₂ + b₃	+2 -2	-4 -2	-6 -4	-3 -3	-5 -1	-1 -3	-b₃	b₁	b₂ - b₁	b₃ - b₁

Table 3.1.2.5
Discussion of Gruber's example using the cell surface

No.	(b ₁ ^s , b ₂ ^s , b ₃ ^s)	Homogenous corner	Surface (surface units)
1	(+b _D , +a _D , +c _D)	Non-acute	41.25
2	(+b _D , +a _D , +d _D)	Non-acute	40.83
3	(+b _D , -a _D , b _D + c _D)	Acute	39.61
4	(+b _D , +c _D , +d _D)	Non-acute	41.03
5	(+b _D , -d _D , b _D + c _D)	Acute	40.06

its scalar products before transformation as the first line, and then the transformed scalar products and the Delaunay basis after transformation below. In our case, four transformation steps are necessary. The result is

$$a_D = -b_3, \quad b_D = b_1, \quad c_D = b_2 - b_1, \quad d_D = b_3 - b_1.$$

The final Selling tetrahedron shows that the Dirichlet domain belongs to Voronoi type 1. It fulfils no symmetry condition and thus corresponds to an anorthic (triclinic) lattice.

For further standardization we consider the Delaunay set

$$\{\pm a_D, \pm b_D, \pm c_D, \pm d_D\} \\ = -(a_D + b_D + c_D), \pm(b_D + c_D), \pm(a_D + c_D), \pm(a_D + b_D)\}.$$

All bases of shortest lattice vectors (b₁^s, b₂^s, b₃^s) can be found:

$$|a_D|^2 = 8, \quad |b_D|^2 = 6, \quad |c_D|^2 = 8, \quad |d_D|^2 = 8, \\ |b_D + c_D|^2 = 8, \quad |a_D + c_D|^2 = 12, \quad |a_D + b_D|^2 = 10.$$

Any basis of shortest lattice vectors contains b₁^s = b_D = b₁. For b₂^s the vectors a_D = -b₃, c_D = b₂ - b₁, d_D = b₃ - b₁ and (b_D + c_D) = b₂ are possible. b₃^s can only be chosen from these vectors such that a linear independent triplet results.

The resulting five choices are given in Table 3.1.2.5. Any case corresponds to eight combinations of signs for the three basis vectors. The principle of the 'homogenous corner' (i.e., there is always a pair of opposite corners of the corresponding cell where all angles are either non-acute or all three are acute) selects one of the bases in each case, thus five different bases remain. For the final choice the surfaces of the corresponding cells are given.

The maximal surface has cell No. 1 with the metrical parameters

$$a = 2.449, \quad b = c = 2.828 \text{ \AA}, \quad \alpha = 104.47, \quad \beta = 115.66, \quad \gamma = 106.78^\circ.$$

A last possibility for the standardization is the interchange of b and c with inversion of all basis vectors. In this way the sequence of β and γ can be interchanged:

$$a = 2.449, \quad b = c = 2.828 \text{ \AA}, \quad \alpha = 104.47, \quad \beta = 106.78, \quad \gamma = 115.66^\circ.$$