

1. GENERAL RELATIONSHIPS AND TECHNIQUES

$$\mathcal{F}[f'](\xi) = (2\pi i \xi) \mathcal{F}[f](\xi)$$

with the bound

$$\|2\pi \xi \mathcal{F}[f]\|_\infty \leq \|f'\|_1$$

so that  $|\mathcal{F}[f](\xi)|$  decreases faster than  $1/|\xi| \rightarrow \infty$ .

This result can be easily extended to several dimensions and to any multi-index  $\mathbf{m}$ : if  $f$  is summable and has continuous summable partial derivatives up to order  $|\mathbf{m}|$ , then

$$\mathcal{F}[D^{\mathbf{m}}f](\xi) = (2\pi i \xi)^{\mathbf{m}} \mathcal{F}[f](\xi)$$

and

$$\|(2\pi \xi)^{\mathbf{m}} \mathcal{F}[f]\|_\infty \leq \|D^{\mathbf{m}}f\|_1.$$

Similar results hold for  $\tilde{\mathcal{F}}$ , with  $2\pi i \xi$  replaced by  $-2\pi i \xi$ . Thus, the more differentiable  $f$  is, with summable derivatives, the faster  $\mathcal{F}[f]$  and  $\tilde{\mathcal{F}}[f]$  decrease at infinity.

The property of turning differentiation into multiplication by a monomial has many important applications in crystallography, for instance differential syntheses (Sections 1.3.4.2.1.9, 1.3.4.4.7.2, 1.3.4.4.7.5) and moment-generating functions [Section 1.3.4.5.2.1(c)].

1.3.2.4.2.9. *Decrease at infinity*

Conversely, assume that  $f$  is summable on  $\mathbb{R}^n$  and that  $f$  decreases fast enough at infinity for  $\mathbf{x}^{\mathbf{m}}f$  also to be summable, for some multi-index  $\mathbf{m}$ . Then the integral defining  $\mathcal{F}[f]$  may be subjected to the differential operator  $D^{\mathbf{m}}$ , still yielding a convergent integral: therefore  $D^{\mathbf{m}}\mathcal{F}[f]$  exists, and

$$D^{\mathbf{m}}(\mathcal{F}[f])(\xi) = \mathcal{F}[(-2\pi i \mathbf{x})^{\mathbf{m}}f](\xi)$$

with the bound

$$\|D^{\mathbf{m}}(\mathcal{F}[f])\|_\infty = \|(2\pi \mathbf{x})^{\mathbf{m}}f\|_1.$$

Similar results hold for  $\tilde{\mathcal{F}}$ , with  $-2\pi i \mathbf{x}$  replaced by  $2\pi i \mathbf{x}$ . Thus, the faster  $f$  decreases at infinity, the more  $\mathcal{F}[f]$  and  $\tilde{\mathcal{F}}[f]$  are differentiable, with bounded derivatives. This property is the converse of that described in Section 1.3.2.4.2.8, and their combination is fundamental in the definition of the function space  $\mathcal{S}$  in Section 1.3.2.4.4.1, of tempered distributions in Section 1.3.2.5, and in the extension of the Fourier transformation to them.

1.3.2.4.2.10. *The Paley–Wiener theorem*

An extreme case of the last instance occurs when  $f$  has compact support: then  $\mathcal{F}[f]$  and  $\tilde{\mathcal{F}}[f]$  are so regular that they may be analytically continued from  $\mathbb{R}^n$  to  $\mathbb{C}^n$  where they are entire functions, i.e. have no singularities at finite distance (Paley & Wiener, 1934). This is easily seen for  $\mathcal{F}[f]$ : giving vector  $\xi \in \mathbb{R}^n$  a vector  $\eta \in \mathbb{R}^n$  of imaginary parts leads to

$$\begin{aligned} \mathcal{F}[f](\xi + i\eta) &= \int_{\mathbb{R}^n} f(\mathbf{x}) \exp[-2\pi i(\xi + i\eta) \cdot \mathbf{x}] d^n \mathbf{x} \\ &= \mathcal{F}[\exp(2\pi \eta \cdot \mathbf{x})f](\xi), \end{aligned}$$

where the latter transform always exists since  $\exp(2\pi \eta \cdot \mathbf{x})f$  is summable with respect to  $\mathbf{x}$  for all values of  $\eta$ . This analytic continuation forms the basis of the saddlepoint method in probability theory [Section 1.3.4.5.2.1(f)] and leads to the use of maximum-entropy distributions in the statistical theory of direct phase determination [Section 1.3.4.5.2.2(e)].

By Liouville's theorem, an entire function in  $\mathbb{C}^n$  cannot vanish identically on the complement of a compact subset of  $\mathbb{R}^n$  without vanishing everywhere: therefore  $\mathcal{F}[f]$  cannot have compact support if  $f$  has, and hence  $\mathcal{Q}(\mathbb{R}^n)$  is not stable by Fourier transformation.

1.3.2.4.3. *Fourier transforms in  $L^2$*

Let  $f$  belong to  $L^2(\mathbb{R}^n)$ , i.e. be such that

$$\|f\|_2 = \left( \int_{\mathbb{R}^n} |f(\mathbf{x})|^2 d^n \mathbf{x} \right)^{1/2} < \infty.$$

1.3.2.4.3.1. *Invariance of  $L^2$*

$\mathcal{F}[f]$  and  $\tilde{\mathcal{F}}[f]$  exist and are functions in  $L^2$ , i.e.  $\mathcal{F}L^2 = L^2$ ,  $\tilde{\mathcal{F}}L^2 = L^2$ .

1.3.2.4.3.2. *Reciprocity*

$\mathcal{F}[\tilde{\mathcal{F}}[f]] = f$  and  $\tilde{\mathcal{F}}[\mathcal{F}[f]] = f$ , equality being taken as 'almost everywhere' equality. This again leads to calling  $\tilde{\mathcal{F}}$  the 'inverse Fourier transformation' rather than the Fourier cotransformation.

1.3.2.4.3.3. *Isometry*

$\mathcal{F}$  and  $\tilde{\mathcal{F}}$  preserve the  $L^2$  norm:

$$\|\mathcal{F}[f]\|_2 = \|\tilde{\mathcal{F}}[f]\|_2 = \|f\|_2 \text{ (Parseval's/Plancherel's theorem).}$$

This property, which may be written in terms of the inner product  $(\cdot)$  in  $L^2(\mathbb{R}^n)$  as

$$(\mathcal{F}[f], \mathcal{F}[g]) = (\tilde{\mathcal{F}}[f], \tilde{\mathcal{F}}[g]) = (f, g),$$

implies that  $\mathcal{F}$  and  $\tilde{\mathcal{F}}$  are unitary transformations of  $L^2(\mathbb{R}^n)$  into itself, i.e. infinite-dimensional 'rotations'.

1.3.2.4.3.4. *Eigenspace decomposition of  $L^2$*

Some light can be shed on the geometric structure of these rotations by the following simple considerations. Note that

$$\begin{aligned} \mathcal{F}^2[f](\mathbf{x}) &= \int_{\mathbb{R}^n} \mathcal{F}[f](\xi) \exp(-2\pi i \mathbf{x} \cdot \xi) d^n \xi \\ &= \tilde{\mathcal{F}}[\mathcal{F}[f]](-\mathbf{x}) = f(-\mathbf{x}) \end{aligned}$$

so that  $\mathcal{F}^4$  (and similarly  $\tilde{\mathcal{F}}^4$ ) is the identity map. Any eigenvalue of  $\mathcal{F}$  or  $\tilde{\mathcal{F}}$  is therefore a fourth root of unity, i.e.  $\pm 1$  or  $\pm i$ , and  $L^2(\mathbb{R}^n)$  splits into an orthogonal direct sum

$$\mathbf{H}_0 \otimes \mathbf{H}_1 \otimes \mathbf{H}_2 \otimes \mathbf{H}_3,$$

where  $\mathcal{F}$  (respectively  $\tilde{\mathcal{F}}$ ) acts in each subspace  $\mathbf{H}_k$  ( $k = 0, 1, 2, 3$ ) by multiplication by  $(-i)^k$ . Orthonormal bases for these subspaces can be constructed from Hermite functions (cf. Section 1.3.2.4.4.2). This method was used by Wiener (1933, pp. 51–71).

1.3.2.4.3.5. *The convolution theorem and the isometry property*

In  $L^2$ , the convolution theorem (when applicable) and the Parseval/Plancherel theorem are not independent. Suppose that  $f, g, f * g$  and  $f \check{*} g$  are all in  $L^2$  (without questioning whether these properties are independent). Then  $f * g$  may be written in terms of the inner product in  $L^2$  as follows:

$$(f * g)(\mathbf{x}) = \int_{\mathbb{R}^n} f(\mathbf{x} - \mathbf{y})g(\mathbf{y}) d^n \mathbf{y} = \int_{\mathbb{R}^n} \overline{\check{f}(\mathbf{y} - \mathbf{x})}g(\mathbf{y}) d^n \mathbf{y},$$

i.e.

$$(f * g)(\mathbf{x}) = (\tau_{\mathbf{x}} \check{f}, g).$$

Invoking the isometry property, we may rewrite the right-hand side as