2. RECIPROCAL SPACE IN CRYSTAL-STRUCTURE DETERMINATION

from the known portion. In such single-site search procedures, single atoms are placed at all possible positions in a crystal, using a search grid of the same fineness as for the stored Patterson function, preferably about one-third of the resolution of the Patterson map. Solutions are gauged to be acceptable if all expected vectors due to symmetry-related atoms are observed above a specified threshold in the Patterson.

Systematic computerized Patterson search procedures for orienting and positioning known molecular fragments were also developed in the early 1960s. These hierarchical procedures rely on first using the 'self'-vectors which depend only on the orientation of a molecular fragment. A search for the position of the fragment relative to the crystal symmetry elements then uses the cross-vectors between molecules (see Sections 2.3.6 and 2.3.7). Nordman constructed a weighted point representation of the predicted vector set for a fragment (Nordman & Nakatsu, 1963; Nordman, 1966) and successfully solved the structure of a number of complex alkaldoids. Huber (1965) used the convolution molecule method of Hoppe (1957a) in three dimensions to solve a number of natural-product structures, including steroids. Various program systems have used Patterson search methods operating in real space to solve complex structures (Braun et al., 1969; Egert, 1983).

Others have used reciprocal-space procedures for locating known fragments. Tollin & Cochran (1964) developed a procedure for determining the orientation of planar groups by searching for origin-containing planes of high density in the Patterson. General procedures using reciprocal-space representations for determining rotation and translation parameters have been developed and will be described in Sections 2.3.6 and 2.3.7, respectively.

Although as many functions have been used to detect solutions in these Patterson search procedures as there are programs, most rely on some variation of the sum, product and minimum functions (Section 2.3.2.4). The quality of the stored Patterson density representation also varies widely, but it is now common to use 16 or more bits for single density values. Treatment of vector overlap is generally be neglected.

2.3.3.2. Finding heavy atoms with centrosymmetric projections

Phases in a centrosymmetric projection will be 0 or π if the origin is chosen at the centre of symmetry. Hence, the native structure factor, \( F_N \), and the heavy-atom-derivative structure factor, \( F_{NH} \), will be collinear. It follows that the structure amplitude, \( |F_H| \), of the heavy atoms alone in the cell will be given by

\[
|F_H| = |(F_{NH} \pm F_N)| + \varepsilon,
\]

where \( \varepsilon \) is the error on the parentetic sum or difference. Three different cases may arise (Fig. 2.3.3.1). Since the situation shown in Fig. 2.3.3.1(c) is rare, in general

\[
|F_H|^2 \simeq (|F_{NH}| - |F_N|)^2.
\]

Thus, a Patterson computed with the square of the differences between the native and derivative structure amplitudes of a centrosymmetric projection will approximate to a Patterson of the heavy atoms alone.

The approximation (2.3.3.1) is valid if the heavy-atom substitution is small enough to make \( |F_{NH}| \ll |F_N| \) for most reflections, but sufficiently large to make \( \varepsilon \ll (|F_{NH}| - |F_N|)^2 \). It is also assumed that the native and heavy-atom-derivative data have been placed on the same relative scale. Hence, the relation (2.3.3.1) should be re-written as

\[
|F_H|^2 \simeq (|F_{NH}| - k|F_N|)^2,
\]

where \( k \) is an experimentally determined scale factor (see Section 2.3.3.7). Uncertainty in the determination of \( k \) will contribute further to \( \varepsilon \), albeit in a systematic manner.

Centrosymmetric projections were used extensively for the determination of heavy-atom sites in early work on proteins such as haemoglobin (Green et al., 1954), myoglobin (Bluhm et al.,