

5. DYNAMICAL THEORY AND ITS APPLICATIONS

A splitting matrix is introduced to separate the wavefunction into the forward and backward components, ψ_b^\pm , and the fast part of the phase is factored out, so that $\psi_b^\pm = \psi^\pm \exp\{\pm ik_z z\}$. In the resulting matrix differential equation, the off-diagonal terms are seen to be small for fast electrons, and equation (5.2.2.1) reduces to the pair of equations

$$\frac{\partial \psi^\pm}{\partial z} = \pm i \left[\frac{1}{2k_z} (\nabla_{x,y}^2 + K_0^2) + \sigma \varphi \right] \psi^\pm. \quad (5.2.3.2)$$

The equation for ψ^\pm is the Lontovich & Fock (1946) parabolic equation.

5.2.4. Evolution operator

Equation (5.2.3.1) is a standard and much studied form, so that many techniques are available for the construction of solutions. One of the most direct utilizes the causal evolution operator. A recent account is given by Gratiias & Portier (1983).

In terms of the 'Hamiltonian' of the two-dimensional system,

$$-\mathbf{H}(z) \equiv \frac{1}{2k_z} (\nabla_{x,y}^2 + K_0^2) + \sigma \varphi,$$

the evolution operator $\mathbf{U}(z, z_0)$, defined by $\psi(z) = \mathbf{U}(z, z_0)\psi_0$, satisfies

$$i \frac{\partial}{\partial z} \mathbf{U}(z, z_0) = \mathbf{H}(z) \mathbf{U}(z, z_0), \quad (5.2.4.1a)$$

or

$$\mathbf{U}(z, z_0) = 1 - i \int_{z_0}^z \mathbf{U}(z, z_1) \mathbf{H}(z_1) dz_1. \quad (5.2.4.1b)$$

5.2.5. Projection approximation – real-space solution

Many of the features of the more general solutions are retained in the practically important projection approximation in which $\varphi(x, y, z)$ is replaced by its projected mean value $\varphi_p(x, y)$, so that the corresponding Hamiltonian \mathbf{H}_p does not depend on z . Equation (5.2.4.1b) can then be solved directly by iteration to give

$$\mathbf{U}_p(z, z_0) = \exp\{-i\mathbf{H}_p(z - z_0)\}, \quad (5.2.5.1)$$

and the solution may be verified by substitution into equation (5.2.4.1a).

Many of the results of dynamical theory can be obtained by expansion of equation (5.2.5.1) as

$$\mathbf{U}_p \equiv \mathbf{1} - i\mathbf{H}_p(z - z_0) + \frac{i^2}{2!} \mathbf{H}_p^2(z - z_0) - \dots,$$

followed by the direct evaluation of the differentials. Such expressions can be used, for instance, to explore symmetries in image space.

5.2.6. Semi-reciprocal space

In the derivation of electron-diffraction equations, it is more usual to work in semi-reciprocal space (Tournarie, 1962). This can

be achieved by transforming equation (5.2.2.1) with respect to x and y but not with respect to z , to obtain Tournarie's equation

$$\frac{d^2 |U\rangle}{dz^2} = -\mathbf{M}_b(z) |U\rangle. \quad (5.2.6.1a)$$

Here $|U\rangle$ is the column vector of scattering amplitudes and $\mathbf{M}_b(z)$ is a matrix, appropriate to LEED, with \mathbf{k} vectors as diagonal elements and Fourier coefficients of the potential as nondiagonal elements.

This equation is factorized in a manner parallel to that used on the real-space equation [equation (5.2.3.1)] (Lynch & Moodie, 1972) to obtain Tournarie's forward-scattering equation

$$\frac{d|U^\pm\rangle}{dz} = \pm i \mathbf{M}^\pm(z) |U^\pm\rangle, \quad (5.2.6.1b)$$

where

$$\begin{aligned} \mathbf{M}^\pm(z) &= \pm [\mathbf{K} + (1/2)\mathbf{K}^{-1}V(z)], \\ [K_{ij}] &= \delta_{ij}K_i, \end{aligned}$$

and

$$[V_{ij}] = 2k_z \sum_l V_{i-j} \exp\{-2\pi i l z\},$$

where $V_i \equiv \sigma v_i$ are the scattering coefficients and v_i are the structure amplitudes in volts. In order to simplify the electron-diffraction expression, the third crystallographic index ' l ' is taken to represent the periodicity along the z direction.

The double solution involving \mathbf{M} of equation (5.2.6.1b) is of interest in displaying the symmetry of reciprocity, and may be compared with the double solution obtained for the real-space equation [equation (5.2.3.2)]. Normally the \mathbf{M}^+ solution will be followed through to give the fast-electron forward-scattering equations appropriate in HEED. \mathbf{M}^- , however, represents the equivalent set of equations corresponding to the z reversed reciprocity configuration. Reciprocity solutions will yield diffraction symmetries in the forward direction when coupled with crystal-inverting symmetries (Section 2.5.3).

Once again we set out to solve the forward-scattering equation (5.2.6.1a,b) now in semi-reciprocal space, and define an operator $\mathbf{Q}(z)$ [compare with equation (5.2.4.1a)] such that

$$|U_z\rangle = \mathbf{Q}_z |U_0\rangle \quad \text{with} \quad U_0 = |0\rangle;$$

i.e., \mathbf{Q}_z is an operator that, when acting on the incident wavevector, generates the wavefunction in semi-reciprocal space.

Again, the differential equation can be transformed into an integral equation, and once again this can be iterated. In the projection approximation, with \mathbf{M} independent of z , the solution can be written as

$$\mathbf{Q}_p = \exp\{i\mathbf{M}_p(z - z_0)\}.$$

A typical off-diagonal element is given by $V_{i-j}/\cos\theta_i$, where θ_i is the angle through which the beam is scattered. It is usual in the literature to find that $\cos\theta_i$ has been approximated as unity, since even the most accurate measurements are, so far, in error by much more than this amount.

This expression for \mathbf{Q}_p is Sturkey's (1957) solution, a most useful relation, written explicitly as