

1. TENSORIAL ASPECTS OF PHYSICAL PROPERTIES

where B is the symmetry operation. Through identification of homologous coefficients in matrices T and BTB^T , one obtains relations between components t_{ij} that enable the determination of the independent components.

1.1.4.6.3. The method of direct inspection

The method of ‘direct inspection’, due to Fumi (1952a,b, 1987), is very simple. It is based on the fundamental properties of tensors; the components transform under a change of basis like a product of vector components (Section 1.1.3.2).

Examples

(1) Let us consider a tensor of rank 3 invariant with respect to a twofold axis parallel to Ox_3 . The matrix representing this operator is

$$\begin{pmatrix} \bar{1} & 0 & 0 \\ 0 & \bar{1} & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

The component t_{ijk} behaves under a change of axes like the product of the components x_i, x_j, x_k . The components x_1, x_2, x_3 of a vector become, respectively, $-x_1, -x_2, x_3$. To simplify the notation, we shall denote the components of the tensor simply by ijk . If, amongst the indices i, j and k , there is an even number (including the number zero) of indices that are equal to 3, the product $x_i x_j x_k$ will become $-x_i x_j x_k$ under the rotation. As the component ‘ ijk ’ remains invariant and is also equal to its opposite, it must be zero. 14 components will thus be equal to zero:

111, 122, 133, 211, 222, 133, 112, 121, 212, 221, 323, 331, 332, 313.

(2) Let us now consider that the same tensor of rank 3 is invariant with respect to a fourfold axis parallel to Ox_3 . The matrix representing this operator and its action on a vector of coordinates x_1, x_2, x_3 is given by

$$\begin{pmatrix} x_2 \\ -x_1 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ \bar{1} & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}. \tag{1.1.4.3}$$

Coordinate x_1 becomes x_2 , x_2 becomes $-x_1$ and x_3 becomes x_3 . Component ijk transforms like product $x^i x^j x^k$ according to the rule given above. Since the twofold axis parallel to Ox_3 is a subgroup of the fourfold axis, we can start from the corresponding reduction. We find

$$\begin{array}{lll} 311 & \iff & 322 : t_{311} = t_{322} \\ 123 & \iff & -(213) : t_{123} = -t_{213} \\ 113 & \iff & 223 : t_{113} = t_{223} \\ 333 & \iff & 333 : t_{333} = t_{333} \\ 132 & \iff & -(231) : t_{132} = -t_{231} \\ 131 & \iff & 232 : t_{131} = t_{232} \\ 312 & \iff & -(321) : t_{312} = -t_{321}. \end{array}$$

All the other components are equal to zero.

It is not possible to apply the method of direct inspection for point group 3. One must in this case use the matrix method described in Section 1.1.4.6.2; once this result is assumed, the method can be applied to all other point groups.

1.1.4.7. Reduction of the components of a tensor of rank 2

The reduction is given for each of the 11 Laue classes.

1.1.4.7.1. Triclinic system

Groups $\bar{1}, 1$: no reduction, the tensor has 9 independent components. The result is represented in the following symbolic way (Nye, 1957, 1985):

$$\begin{pmatrix} \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet \end{pmatrix}$$

where the sign \bullet represents a nonzero component.

1.1.4.7.2. Monoclinic system

Groups $2m, 2, m$: it is sufficient to consider the twofold axis or the mirror. As the representative matrix is diagonal, the calculation is immediate. Taking the twofold axis to be parallel to Ox_3 , one has

$$t_3^1 = t_1^3 = t_3^2 = t_2^3 = 0.$$

The other components are not affected. The result is represented as

$$\begin{pmatrix} \bullet & \bullet & \\ \bullet & \bullet & \\ & & \bullet \end{pmatrix}$$

There are 5 independent components. If the twofold axis is taken along axis Ox_2 , which is the usual case in crystallography, the table of independent components becomes

$$\begin{pmatrix} \bullet & & \bullet \\ & \bullet & \\ \bullet & & \bullet \end{pmatrix}$$

1.1.4.7.3. Orthorhombic system

Groups $mmm, 2mm, 222$: the reduction is obtained by considering two perpendicular twofold axes, parallel to Ox_3 and to Ox_2 , respectively. One obtains

$$\begin{pmatrix} \bullet & & \\ & \bullet & \\ & & \bullet \end{pmatrix}$$

There are 3 independent components.

1.1.4.7.4. Trigonal, tetragonal, hexagonal and cylindrical systems

We remarked in Section 1.1.4.6.2.3 that, in the case of tensors of rank 2, the reduction is the same for threefold, fourfold or sixfold axes. It suffices therefore to perform the reduction for the tetragonal groups. That for the other systems follows automatically.

1.1.4.7.4.1. Groups $\bar{3}, 3; 4/m, \bar{4}, 4; 6/m, \bar{6}, 6; (A_\infty/M)C, A_\infty$

If we consider a fourfold axis parallel to Ox_3 represented by the matrix given in (1.1.4.3), by applying the direct inspection method one finds

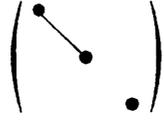
$$\begin{pmatrix} \bullet & \ominus & \bullet \\ \ominus & \bullet & \\ & & \bullet \end{pmatrix}$$

where the symbol \ominus means that the corresponding component is numerically equal to that to which it is linked, but of opposite sign. There are 3 independent components.

1.1. INTRODUCTION TO THE PROPERTIES OF TENSORS

1.1.4.7.4.2. Groups $\bar{3}m$, 32 , $3m$; $4/m\bar{m}$, 422 , $4mm$, $\bar{4}2m$; $6/m\bar{m}$, 622 , $6mm$, $62m$; $(A_\infty/M) \propto (A_2/M)C$, $A_\infty \propto A_2$

The result is obtained by combining the preceding result and that corresponding to a twofold axis normal to the fourfold axis. One finds



There are 2 independent components.

1.1.4.7.5. Cubic and spherical systems

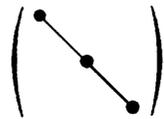
The cubic system is characterized by the presence of threefold axes along the $\langle 111 \rangle$ directions. The action of a threefold axis along $[111]$ on the components x_1, x_2, x_3 of a vector results in a permutation of these components, which become, respectively, x_2, x_3, x_1 and then x_3, x_1, x_2 . One deduces that the components of a tensor of rank 2 satisfy the relations

$$t_1^1 = t_2^2 = t_3^3.$$

The cubic groups all include as a subgroup the group 23 of which the generating elements are a twofold axis along Ox_3 and a threefold axis along $[111]$. If one combines the corresponding results, one deduces that

$$t_1^2 = t_2^3 = t_3^1 = t_1^3 = t_2^1 = t_3^2 = 0,$$

which can be summarized by

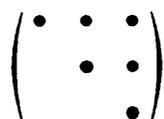


There is a single independent component and the medium behaves like a property represented by a tensor of rank 2, like an isotropic medium.

1.1.4.7.6. Symmetric tensors of rank 2

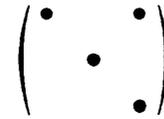
If the tensor is symmetric, the number of independent components is still reduced. One obtains the following, representing the nonzero components for the leading diagonal and for one half of the others.

1.1.4.7.6.1. Triclinic system



There are 6 independent components. It is possible to interpret the number of independent components of a tensor of rank 2 by considering the associated quadric, for instance the optical indicatrix. In the triclinic system, the quadric is any quadric. It is characterized by six parameters: the lengths of the three axes and the orientation of these axes relative to the crystallographic axes.

1.1.4.7.6.2. Monoclinic system (twofold axis parallel to Ox_2)



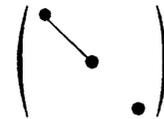
There are 4 independent components. The quadric is still any quadric, but one of its axes coincides with the twofold axis of the monoclinic lattice. Four parameters are required: the lengths of the axes and one angle.

1.1.4.7.6.3. Orthorhombic system



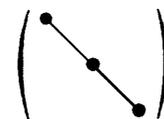
There are 3 independent components. The quadric is any quadric, the axes of which coincide with the crystallographic axes. Only three parameters are required.

1.1.4.7.6.4. Trigonal, tetragonal and hexagonal systems, isotropic groups



There are 2 independent components. The quadric is of revolution. It is characterized by two parameters: the lengths of its two axes.

1.1.4.7.6.5. Cubic system



There is 1 independent component. The associated quadric is a sphere.

1.1.4.8. Reduction of the components of a tensor of rank 3

1.1.4.8.1. Triclinic system

1.1.4.8.1.1. Group 1

All the components are independent. Their number is equal to 27. They are usually represented as a 3×9 matrix which can be subdivided into three 3×3 submatrices:

$$\begin{pmatrix} 111 & 122 & 133 & 123 & 131 & 112 & 132 & 113 & 121 \\ 211 & 222 & 233 & 223 & 231 & 212 & 232 & 213 & 221 \\ 311 & 322 & 333 & 323 & 331 & 312 & 332 & 313 & 321 \end{pmatrix}.$$

1.1.4.8.1.2. Group $\bar{1}$

All the components are equal to zero.