

1.4. THERMAL EXPANSION

$$n(\omega_s, T) = \frac{1}{\exp(\hbar\omega_s/kT) - 1}. \quad (1.4.2.7)$$

Differentiation of (1.4.2.5) and (1.4.2.6) with respect to temperature at constant volume [see (1.4.2.1)] yields

$$\begin{aligned} \left(\frac{\partial p}{\partial T}\right)_V &= - \sum_s \sum_t \hbar \frac{\partial n(\omega_s, T)}{\partial T} \frac{\partial \omega_s(\mathbf{q}_t)}{\partial V} \\ &= - \sum_s \sum_t c_{s,t}^V \frac{1}{\omega_s(\mathbf{q}_t)} \frac{\partial \omega_s(\mathbf{q}_t)}{\partial V} \end{aligned} \quad (1.4.2.8)$$

with

$$c_{s,t}^V = \hbar\omega_s(\mathbf{q}_t) \frac{\partial n(\omega_s, T)}{\partial T} = k \frac{(\hbar\omega_s/kT)^2 \exp(\hbar\omega_s/kT)}{[\exp(\hbar\omega_s/kT) - 1]^2}. \quad (1.4.2.9)$$

This quantity, $c_{s,t}^V$ (the Einstein function), is the well known contribution of the normal mode $\omega_s(\mathbf{q}_t)$ to the specific heat (at constant volume):

$$c^V = \sum_s \sum_t c_{s,t}^V = \sum_s \sum_t \hbar\omega_s(\mathbf{q}_t) \frac{\partial n(\omega_s, T)}{\partial T}. \quad (1.4.2.10)$$

Equation (1.4.2.8) can be simplified by the introduction of an ‘individual Grüneisen parameter’ $\gamma_{s,t}$ for each normal mode $\omega_s(\mathbf{q}_t)$:

$$\gamma_{s,t} = - \frac{V}{\omega_s(\mathbf{q}_t)} \frac{\partial \omega_s(\mathbf{q}_t)}{\partial V} = - \frac{\partial[\ln \omega_s(\mathbf{q}_t)]}{\partial(\ln V)}. \quad (1.4.2.11)$$

Equation (1.4.2.8) then reads [with (1.4.2.1)]

$$\left(\frac{\partial p}{\partial T}\right)_V = \frac{1}{V} \sum_s \sum_t c_{s,t}^V \gamma_{s,t} = \frac{\beta}{\kappa}. \quad (1.4.2.12)$$

Based on these individual parameters $\gamma_{s,t}$, an average (or overall mode-independent) Grüneisen parameter $\bar{\gamma}$ can be defined as

$$\bar{\gamma} = \frac{\sum_s \sum_t \gamma_{s,t} c_{s,t}^V}{\sum_s \sum_t c_{s,t}^V} = \frac{\sum_s \sum_t \gamma_{s,t} c_{s,t}^V}{c^V}. \quad (1.4.2.13)$$

In this averaging process, the contribution of each normal mode to $\bar{\gamma}$ is weighted in the same way as it contributes to the specific heat c^V [see (1.4.2.10)]. Equations (1.4.2.12) and (1.4.2.13) lead to the Grüneisen relation

$$\beta = \bar{\gamma} \frac{\kappa c^V}{V}. \quad (1.4.2.14)$$

The above derivation was made for isotropic media. For anisotropic media, $\Delta V/V$ is replaced by the strain u_{kl} and κ^{-1} is replaced by the stiffness tensor c_{ijkl} [cf. Chapter 2.1 and equation (2.1.2.75)]. Then the Grüneisen parameter turns out to be a second-rank tensor γ_{ij} :

$$\gamma_{ij} = \frac{V}{c^V} c_{ijkl}^T \alpha_{kl}. \quad (1.4.2.15)$$

In the Debye approximation, the mode frequencies scale linearly with the cut-off frequency ω_D . Therefore, with $\hbar\omega_D = kT_D$, the average isotropic Grüneisen parameter is calculated to be

$$\gamma_D = - \frac{V}{\omega_D} \frac{\partial \omega_D}{\partial V} = - \frac{V}{T_D} \frac{\partial T_D}{\partial V} = - \frac{\partial(\ln T_D)}{\partial(\ln V)}.$$

Since, in the Debye theory, T_D is independent of temperature, γ_D turns out to be independent of temperature. As κ and V are only weakly temperature dependent, the thermal expansion β should then, according to (1.4.2.14), roughly behave like c^V , *i.e.* β should be proportional to T^3 at very low temperatures, and should be approximately constant for $T \gg T_D$ (the Dulong–Petit law). This

behaviour is found to be approximately satisfied for many compounds, even with different types of interatomic interaction, and γ takes values roughly between 1 and 2. Even in the case of crystals with highly anisotropic elastic and thermal behaviour, the three principal values of the tensor γ_{ij} [(1.4.2.15)] are comparably uniform, having values of about 2 (Küppers, 1974).

Effectively, γ shows a certain more or less pronounced dependence on temperature. The individual $\gamma_{s,t}$ are assumed to be temperature independent. However, being an average over the whole spectrum of excited modes [cf. (1.4.2.13)], $\bar{\gamma}$ will not necessarily have the same value at low temperatures (when only low frequencies are excited) as at high temperatures (when all modes are excited). Two limiting cases can be considered:

(1) At very high temperatures, all normal modes contribute by an equal amount and the overall $\bar{\gamma}$ becomes simply the mean value of all $\gamma_{s,t}$.

$$\gamma_\infty = \frac{1}{3pN} \sum_s \sum_t \gamma_{s,t}.$$

(2) At very low temperatures, only the lower frequencies contribute. If only the acoustic branches are considered, $\bar{\gamma}$ can be related to the velocities of elastic waves. In the long-wavelength limit, dispersion is neglected, *i.e.* $|\mathbf{q}|$ is proportional to ω :

$$|\mathbf{q}_t| = \frac{\omega_s(\mathbf{q}_t)}{v_s(\varphi, \vartheta)}, \quad (1.4.2.16)$$

where $v_s(\varphi, \vartheta)$ ($s = 1, 2, 3$) describes the velocities of the three elastic waves propagating in a direction (φ, ϑ) . The density of vibrational states for each acoustic branch in reciprocal space increases with $q^2 dq$. From (1.4.2.16), it follows that the number of normal modes in an increment of solid angle in \mathbf{q} space, $d\Omega = \sin \vartheta d\vartheta d\varphi$, within a frequency interval ω to $\omega + d\omega$, is proportional to $(\omega^2 d\omega d\Omega)/v^3$. The summation over t can be converted into an integration over ω and Ω , leading to

$$\gamma_0 = \frac{\sum_{s=1}^3 \int \frac{\gamma_s(\vartheta, \varphi) d\Omega}{v_s^3(\vartheta, \varphi)}}{\sum_{s=1}^3 \int \frac{d\Omega}{v^3(\vartheta, \varphi)}}.$$

The $v_s(\varphi, \vartheta)$ can be calculated if the elastic constants are known. For isotropic solids, the term $\sum v_s^{-3}$ can be replaced (as done in Debye’s theory of heat capacity) by $(v_l^{-3} + 2v_{tr}^{-3})$, with v_l being the velocity of the longitudinal wave and v_{tr} the velocity of the transverse waves.

In metals, the conduction electrons and magnetic interactions yield contributions to the free energy and to the specific heat. Accordingly, expression (1.4.2.14) can be augmented by introduction of an ‘electronic Grüneisen parameter’, γ_e , and a ‘magnetic Grüneisen parameter’, γ_m , in addition to the ‘lattice Grüneisen parameter’, γ_l , considered so far:

$$\beta = \frac{\kappa}{V} (\gamma_l c_l^V + \gamma_e c_e^V + \gamma_m c_m^V).$$

1.4.3. Experimental methods

1.4.3.1. General remarks

Although the strain tensor u_{ij} and the thermal expansion tensor α_{ij} in general contain components with $i \neq j$ (shear strains), in practice only longitudinal effects, *i.e.* relative length changes $\Delta l/l$ with temperature changes ΔT , are measured along different directions and the results are later transformed to a common coordinate system. Diffraction methods directly yield this ratio $\Delta l/l$. Other measuring techniques require separate measurements of Δl and l . The error in the measurement of l can

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usually be neglected. Thus, the accuracies of Δl and ΔT limit the accuracy of thermal expansion coefficients. The temperature interval ΔT is determined by two measurements of temperatures $T_2 > T_1$, with $T_2 - T_1 = \Delta T$. To increase the accuracy of the difference ΔT , this interval should be large. The measured thermal expansion $\Delta l/(l\Delta T)$ is usually assigned to a temperature at the midpoint of the temperature interval, $T_0 = (T_2 - T_1)/2$. This procedure is only justified if thermal expansion does not depend on temperature.

Since, in fact, thermal expansion depends on temperature, in principle, smaller intervals should be chosen, which, in turn, enlarge the error of ΔT . Here, a compromise has to be made. Sometimes, after completion of a first run and after reviewing the preliminary course of $\alpha(T)$, it is necessary to repeat some measurements using smaller temperature intervals in temperature ranges with large curvatures.

The more-or-less curved course of $\alpha_{ij}(T)$ is usually fitted by polynomials in powers of temperature. Here, those T terms should be selected that are physically meaningful in the particular temperature range. For the low-temperature behaviour of a metal, a polynomial of type $\alpha = AT + BT^3 + CT^5$ should be chosen. For minerals at higher temperatures, a polynomial $\alpha = \alpha_0 + AT + BT^{-1} + CT^{-2}$ is used (Saxena & Shen, 1992).

Temperature is usually measured by thermocouples and, in the cases of optical or electrical measurements (Sections 1.4.3.3 and 1.4.3.4) and at low temperatures also by platinum resistance thermometers. Above 1100 K, optical pyrometers can be used.

In order to measure the thermal expansion of a crystal, at least as many independent measurements are necessary as the tensor has independent components (fourth column in Table 1.4.1.1). It is advisable, however, to carry out more measurements than are necessary. In this case (of redundancy), a 'best' set of tensor components is to be determined by least-squares methods as described below.

Let us assume the most general case of a triclinic crystal, where $m > 6$ independent measurements of thermal expansions b_k ($k = 1, \dots, m$) were performed along m different directions with direction cosines $(\alpha_{ij})_k$ ($j = 1, 2, 3$) with respect to the chosen coordinate system. Each measurement b_k is related to the six unknown tensor components α_{ij} (to be determined) by

$$b_k = (\alpha'_{11})_k = (\alpha_{1i})_k(\alpha_{1j})_k\alpha_{ij}. \quad (1.4.3.1)$$

If the α_{ij} are replaced by α_γ ($\gamma = 1, \dots, 6$), using Voigt's one-index notation (Section 1.1.4.10.2), then $b_k = C_{k\gamma}\alpha_\gamma$ represents an overdetermined inhomogeneous system of m linear equations for the six unknowns α_γ . The coefficients $C_{k\gamma}$, forming an $m \times 6$ matrix, are products containing direction cosines according to (1.4.3.1). The solution is obtained after several matrix calculations which are indicated by the formula (Nye, 1985)

$$\alpha_\gamma = \left\{ \left[(C_{l\delta}^t \cdot C_{l\epsilon}^t)^{-1} \right]_{\gamma\eta} C_{k\eta}^t \right\} b_k \\ (\gamma, \delta, \epsilon, \eta = 1, \dots, 6; \quad l, k = 1, \dots, m),$$

where a superscript 't' means transposed.

Instead of determining the tensor components of a triclinic or monoclinic crystal in a direct way, as outlined above, it is also possible to determine first the temperature change of the crystallographic unit cell and then, by formulae given *e.g.* by Schlenker *et al.* (1978), to deduce the tensor components α_{ij} . The direct approach is recommended, however, for reasons of the propagation of errors (Jessen & Küppers, 1991).

The experimental techniques of measuring relative length changes $\Delta l/l$ that are most widely used include diffraction, optical interferometry, pushrod dilatometry and electrical capacitance methods. If the specimens available are very small and/or irregular in shape, only diffraction methods can be used. The other methods require single-crystal parallelepipedal samples with at least 5 mm side lengths.

1.4.3.2. Diffraction

Thermal expansion expresses itself, on a microscopic scale, by a change of the interplanar spacings of lattice planes. These can be measured by use of diffraction methods from changes of Bragg angles θ . Differentiation of the Bragg equation $2d \sin \theta = \lambda$, giving $\Delta d/d = -\cot \theta \Delta \theta$, yields the thermal expansions α'_{11} in directions normal to lattice planes (hkl) (*i.e.* along $\mathbf{h} = h\mathbf{a}^* + k\mathbf{b}^* + l\mathbf{c}^*$) and, if \mathbf{h} has direction cosines $a_{ij}^{(hkl)}$ with respect to the chosen Cartesian coordinate system,

$$\alpha'_{11}{}^{(hkl)} = a_{1i}^{(hkl)} a_{1j}^{(hkl)} \alpha_{ij} = \frac{1}{d^{(hkl)}} \frac{\partial d^{(hkl)}}{\partial T} = -\cot \theta \frac{\partial \theta}{\partial T}.$$

The coefficient $\cot \theta$ permits a tremendous increase of sensitivity and accuracy if $\theta \rightarrow 90^\circ$. That means, if possible, high-angle ($\theta > 70^\circ$) reflections should be used for measurement because, for a given Δd , the changes of Bragg angles $|\Delta \theta|$ to be measured increase with $(\cot \theta)^{-1} = \tan \theta$.

The most important diffraction techniques (X-radiation is preferentially used) are: the rotating-crystal method, the Weissenberg method and diffractometers with counter recording. If small single crystals ($>$ approximately 50 μm) are not available, powder methods (using a Debye-Scherrer film camera or powder diffractometer) must be used, although the advantage of the highly accurate back-reflections, in general, cannot be used.

Experimental aspects of measuring absolute d -values are discussed in detail in Volume C of *International Tables for Crystallography* (1999), Part 5. Since only relative displacements are to be measured in the present case, many complications connected with the determination of absolute values do not apply for thermal expansion measurements, such as zero-point correction, eccentricity of the mounted sample, refraction, absorption and diffraction profile.

1.4.3.3. Optical methods (interferometry)

The basic principle of measuring thermal expansion by interferometry consists of converting sample-length changes into variations of optical path differences of two coherent monochromatic light beams, which are reflected from two opposite end faces of the sample (or planes corresponding to them). An He-Ne laser usually serves as a light source. A beam expander produces a parallel beam and interference by two planes, which are slightly inclined to each other, produces fringes of equal thickness. Thermal expansion causes a movement of this fringe pattern, which is detected by photodiodes. The number of fringes passing a reference mark is counted and gives a measure of the relative movement of the two planes.

As examples for various realizations of interferometric devices (Hahn, 1998), two basic designs will be described.

(i) *Fizeau interferometer* (Fig. 1.4.3.1). The sample S is covered by a thin plate P_2 (with a polished upper surface and a coarsely ground and non-reflecting lower surface) and is placed in between a bottom plate P_3 and a wedge-shaped plate P_1 (wedge angle of about 1°). The upper surface of P_1 reflects the incident beam (i) to a reflected beam (r) so that it is removed from the interference process. The relevant interference takes place between ray (1) reflected by the lower surface of P_1 and ray (2) reflected by the upper surface of P_2 . A cylindrical tube T , which defines the distance between P_1 and P_3 as well as P_2 , is usually made of fused silica, a material of low and well known thermal expansion. The measured dilatation is caused, therefore, by the difference between thermal expansion of the sample and a portion of the fused silica tube of equal length. The whole apparatus is mounted in a thermostat.

(ii) *Michelson interferometer* (Fig. 1.4.3.2). The reference mirror M and the beam-splitter B are placed outside the thermostat. The upper face of the sample S is one interference plane and the upper surface of the bottom plate is the other. The