Furthermore, the left-hand term of (1.1.4.11) remains unchanged if we interchange the indices i and j. The terms on the right-hand side therefore also remain unchanged, whatever the value of T_{ll} or T_{kl}. It follows that

$$s_{ijll} = s_{jill}$$
$$s_{ijkl} = s_{ijlk} = s_{jikl} = s_{jilk}.$$

Similar relations hold for c_{ijkl}, Q_{ijkl}, p_{ijkl} and π_{ijkl}: the submatrices **2** and **3**, **4** and **7**, **5**, **6**, **8** and **9**, respectively, are equal.

Equation (1.4.1.11) can be rewritten, introducing the coefficients of the Voigt strain matrix:

$$S_\alpha = S_{ii} = \sum_l s_{iill} T_{ll} + \sum_{k \neq l} (s_{iikl} + s_{iilk}) T_{kl} \quad (\alpha = 1, 2, 3)$$
$$S_\alpha = S_{ij} + S_{ji} = \sum_l (s_{ijll} + s_{jill}) T_{ll} + \sum_{k \neq l} (s_{ijkl} + s_{ijlk} + s_{jikl} + s_{jilk}) T_{kl} \quad (\alpha = 4, 5, 6).$$

We shall now introduce a two-index notation for the elastic compliances, according to the following conventions:

$$\left.\begin{array}{llll} i = j; & k = l; & s_{\alpha\beta} = s_{iill} \\ i = j; & k \neq l; & s_{\alpha\beta} = s_{iikl} + s_{iilk} \\ i \neq j; & k = l; & s_{\alpha\beta} = s_{ijkk} + s_{jikk} \\ i \neq j; & k \neq l; & s_{\alpha\beta} = s_{ijkl} + s_{jikl} + s_{ijlk} + s_{jilk}. \end{array}\right\} \quad (1.1.4.12)$$

We have thus associated with the fourth-rank tensor a square 6×6 matrix with 36 coefficients:

β / α	1	2	3	4	5	6
1	11	12	13	14	15	16
2	21	22	23	24	25	26
3	31	32	33	34	35	36
4	41	42	43	44	45	46
5	51	52	53	54	55	56
6	61	62	63	64	65	66

One can translate relation (1.1.4.12) using the 9×9 matrix representing s_{ijkl} by adding term by term the coefficients of submatrices **2** and **3**, **4** and **7** and **5**, **6**, **8** and **9**, respectively:

$$\begin{pmatrix} \mathbf{1} \\ \hline \mathbf{2+3} \end{pmatrix} = \begin{pmatrix} \mathbf{1} & \mathbf{2} \\ \hline \mathbf{4+7} & \mathbf{5+6+8+9} \end{pmatrix} \times \begin{pmatrix} \mathbf{1} \\ \hline \mathbf{2+3} \end{pmatrix}$$

Using the two-index notation, equation (1.1.4.9) becomes

$$S_\alpha = s_{\alpha\beta} T_\beta. \quad (1.1.4.13)$$

A similar development can be applied to the other fourth-rank tensors π_{ijkl}, which will be replaced by 6×6 matrices with 36 coefficients, according to the following rules.

(i) *Elastic stiffnesses*, c_{ijkl} and *elasto-optic coefficients*, p_{ijkl}:

$$\begin{pmatrix} \mathbf{1} \\ \hline \mathbf{2} \end{pmatrix} = \begin{pmatrix} \mathbf{1} & \mathbf{2} \\ \hline \mathbf{4} & \mathbf{5} \end{pmatrix} \times \begin{pmatrix} \mathbf{1} \\ \hline \mathbf{2} \end{pmatrix}$$

where

$$c_{\alpha\beta} = c_{ijkl}$$
$$p_{\alpha\beta} = p_{ijkl}.$$

(ii) *Piezo-optic coefficients*, π_{ijkl}:

$$\begin{pmatrix} \mathbf{1} \\ \hline \mathbf{2} \end{pmatrix} = \begin{pmatrix} \mathbf{1} & \mathbf{2+3} \\ \hline \mathbf{4} & \mathbf{5+6} \end{pmatrix} \times \begin{pmatrix} \mathbf{1} \\ \hline \mathbf{2} \end{pmatrix}$$

where

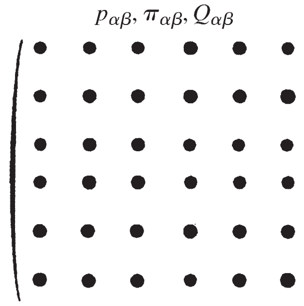
$$\left.\begin{array}{llll} i = j; & k = l; & \pi_{\alpha\beta} = \pi_{iill} \\ i = j; & k \neq l; & \pi_{\alpha\beta} = \pi_{iikl} + \pi_{iilk} \\ i \neq j; & k = l; & \pi_{\alpha\beta} = \pi_{ijkk} = \pi_{jikk} \\ i \neq j; & k \neq l; & \pi_{\alpha\beta} = \pi_{ijkl} + \pi_{jikl} = \pi_{ijlk} + \pi_{jilk}. \end{array}\right\}$$

(iii) *Electrostriction coefficients*, Q_{ijkl}: same relation as for the elastic compliances.

1.1.4.10.6. *Independent components of the matrix associated with a fourth-rank tensor according to the following point groups*

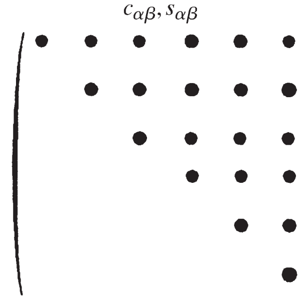
1.1.4.10.6.1. *Triclinic system, groups* $\bar{1}$, 1

$p_{\alpha\beta}, \pi_{\alpha\beta}, Q_{\alpha\beta}$



36 independent components

$c_{\alpha\beta}, s_{\alpha\beta}$

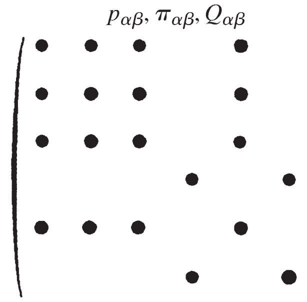


21 independent components

1.1.4.10.6.2. *Monoclinic system*

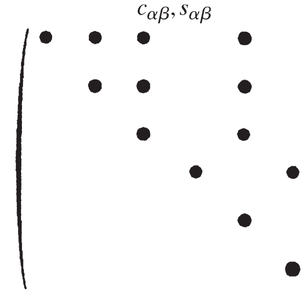
Groups $2/m$, 2, m, twofold axis parallel to Ox_2:

$p_{\alpha\beta}, \pi_{\alpha\beta}, Q_{\alpha\beta}$



20 independent components

$c_{\alpha\beta}, s_{\alpha\beta}$

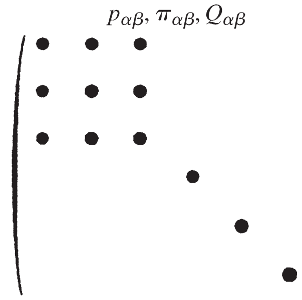


13 independent components

1.1.4.10.6.3. *Orthorhombic system*

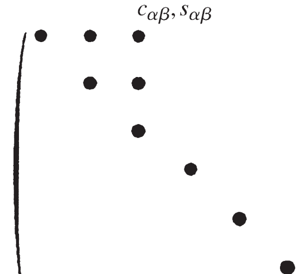
Groups mmm, $2mm$, 222:

$p_{\alpha\beta}, \pi_{\alpha\beta}, Q_{\alpha\beta}$



12 independent components

$c_{\alpha\beta}, s_{\alpha\beta}$



9 independent components

references