

## 3.4. DOMAIN STRUCTURES

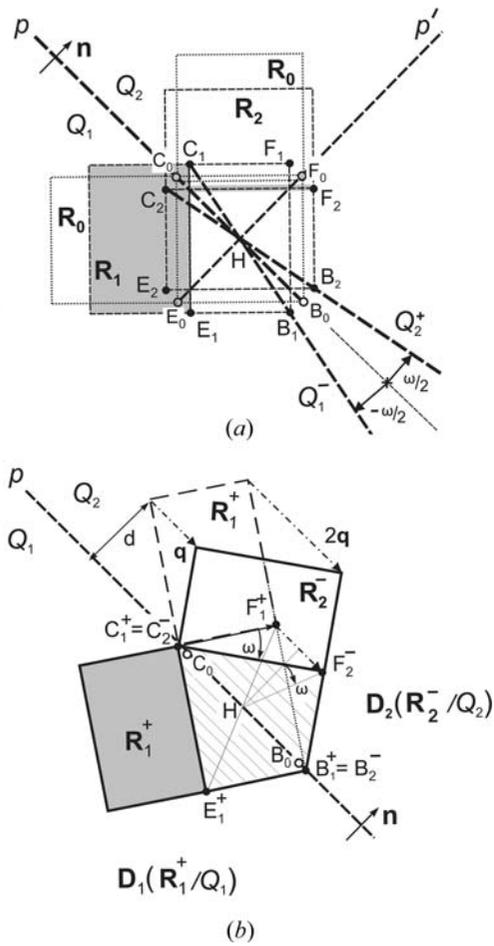


Fig. 3.4.3.5. Two ways of constructing a ferroelastic domain twin. (a) Formation of ferroelastic single-domain states  $\mathbf{R}_1, \mathbf{R}_2$  from the parent phase state  $\mathbf{R}_0$  and then rotating away these single-domain states through an angle  $\pm \frac{1}{2}\omega$  about the domain-pair axis  $H$  so that disoriented ferroelastic domain states  $\mathbf{R}_1^+$  and  $\mathbf{R}_2^-$  meet along one of two perpendicular planes of equal deformation  $p$  or  $p'$ . (b) Formation of a ferroelastic twin from one ferroelastic domain state  $\mathbf{R}_1^+$  by a simple shear deformation with a shear angle (obliquity)  $\omega$ . For more details see the text.

$$\mathbf{u}_{(s)}^{(1)} = \mathbf{u}^{(1)} - \mathbf{u}^{(av)} = \begin{pmatrix} \frac{1}{2}(u_{11} - u_{22}) & 0 & 0 \\ 0 & -\frac{1}{2}(u_{11} - u_{22}) & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad (3.4.3.49)$$

$$\mathbf{u}_{(s)}^{(2)} = \mathbf{u}^{(2)} - \mathbf{u}^{(av)} = \begin{pmatrix} -\frac{1}{2}(u_{11} - u_{22}) & 0 & 0 \\ 0 & \frac{1}{2}(u_{11} - u_{22}) & 0 \\ 0 & 0 & 0 \end{pmatrix}. \quad (3.4.3.50)$$

Symmetry-breaking nonzero components of the relative spontaneous strain are identical, up to the factor  $\frac{1}{2}$ , with the secondary tensor parameters  $\lambda_b^{(1)}$  and  $\lambda_b^{(2)}$  of the transition  $4_z/m_z m_x m_{xy} \supset 2_x m_y m_z$  with the stabilizer  $I_{4_z/m_z m_x m_{xy}}(\mathbf{R}_1) = I_{4_z/m_z m_x m_{xy}}(\mathbf{R}_2) = m_x m_y m_z$ . The non-symmetry-breaking component  $u_{33}$  does not appear in the relative spontaneous strain.

The form of relative spontaneous strains for all ferroelastic domain states of all full ferroelastic phases are listed in Aizu (1970b).

#### 3.4.3.6.2. Equally deformed planes of a ferroelastic domain pair

We start with the example of a phase transition with the symmetry descent  $G = 4_z/m_z m_x m_{xy} \supset 2_x m_y m_z$ , which generates two ferroelastic single-domain states  $\mathbf{R}_1$  and  $\mathbf{R}_2$  (see Fig. 3.4.2.2). An 'elementary cell' of the parent phase is represented in Fig.

3.4.3.5(a) by a square  $B_0E_0C_0F_0$  and the corresponding domain state is denoted by  $\mathbf{R}_0$ .

In the ferro phase, the square  $B_0E_0C_0F_0$  can change either under spontaneous strain  $\mathbf{u}^{(1)}$  into a spontaneously deformed rectangular cell  $B_1E_1C_1F_1$  representing a domain state  $\mathbf{R}_1$ , or under a spontaneous strain  $\mathbf{u}^{(2)}$  into rectangular  $B_2E_2C_2F_2$  representing domain state  $\mathbf{R}_2$ . We shall use the letter  $\mathbf{R}_0$  as a symbol of the parent phase and  $\mathbf{R}_1, \mathbf{R}_2$  as symbols of two ferroelastic single-domain states.

Let us now choose in the parent phase a vector  $\overrightarrow{HB_0}$ . This vector changes into  $\overrightarrow{HB_1}$  in ferroelastic domain state  $\mathbf{R}_1$  and into  $\overrightarrow{HB_2}$  in ferroelastic domain state  $\mathbf{R}_2$ . We see that the resulting vectors  $\overrightarrow{HB_1}$  and  $\overrightarrow{HB_2}$  have different direction but equal length:  $|\overrightarrow{HB_1}| = |\overrightarrow{HB_2}|$ . This consideration holds for any vector in the plane  $p$ , which can therefore be called an *equally deformed plane* (EDP). One can find that the perpendicular plane  $p'$  is also an equally deformed plane, but there is no other plane with this property.

The intersection of the two perpendicular equally deformed planes  $p$  and  $p'$  is a line called an *axis of the ferroelastic domain pair* ( $\mathbf{R}_1, \mathbf{R}_2$ ) (in Fig. 3.4.3.5 it is a line at  $H$  perpendicular to the paper). This axis is the only line in which any vector chosen in the parent phase exhibits equal deformation and has its direction unchanged in both single-domain states  $\mathbf{R}_1$  and  $\mathbf{R}_2$  of a ferroelastic domain pair.

This consideration can be expressed analytically as follows (Fousek & Janovec, 1969; Sapriel, 1975). We choose in the parent phase a plane  $p$  and a unit vector  $\mathbf{v}(x_1, x_2, x_3)$  in this plane. The changes of lengths of this vector in the two ferroelastic domain states  $\mathbf{R}_1$  and  $\mathbf{R}_2$  are  $u_{ik}^{(1)} x_i x_k$  and  $u_{ik}^{(2)} x_i x_k$ , respectively, where  $u_{ik}^{(1)}$  and  $u_{ik}^{(2)}$  are spontaneous strains in  $\mathbf{R}_1$  and  $\mathbf{R}_2$ , respectively (see e.g. Nye, 1985). (We are using the Einstein summation convention: when a letter suffix occurs twice in the same term, summation with respect to that suffix is to be understood.) If these changes are equal, i.e. if

$$u_{ik}^{(1)} x_i x_k = u_{ik}^{(2)} x_i x_k, \quad (3.4.3.51)$$

for any vector  $\mathbf{v}(x_1, x_2, x_3)$  in the plane  $p$ , then this plane will be an *equally deformed plane*. If we introduce a *differential spontaneous strain*

$$\Delta u_{ik} \equiv u_{ik}^{(2)} - u_{ik}^{(1)}, \quad i, k = 1, 2, 3, \quad (3.4.3.52)$$

the condition (3.4.3.51) can be rewritten as

$$\Delta u_{ik} x_i x_j = 0. \quad (3.4.3.53)$$

This equation describes a cone with the apex at the origin. The cone degenerates into two planes if the determinant of the differential spontaneous strain tensor equals zero,

$$\det \Delta u_{ik} = 0. \quad (3.4.3.54)$$

If this condition is satisfied, two solutions of (3.4.3.53) exist:

$$Ax_1 + Bx_2 + Cx_3 = 0, \quad A'x_1 + B'x_2 + C'x_3 = 0. \quad (3.4.3.55)$$

These are equations of two planes  $p$  and  $p'$  passing through the origin. Their normal vectors are  $\mathbf{n} = [ABC]$  and  $\mathbf{n}' = [A'B'C']$ . It can be shown that from the equation

$$\Delta u_{11} + \Delta u_{22} + \Delta u_{33} = 0, \quad (3.4.3.56)$$

which holds for the trace of the matrix  $\det \Delta u_{ik}$ , it follows that these two planes are perpendicular:

$$AA' + BB' + CC' = 0. \quad (3.4.3.57)$$

The intersection of these equally deformed planes (3.4.3.53) is the *axis h of the ferroelastic domain pair* ( $\mathbf{R}_1, \mathbf{R}_2$ ).