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$$d_F = [N_G(F_1) : F_1] = |N_G(F_1)| : |F_1|. \tag{3.4.2.35}$$

The number n_F of subgroups that are conjugate under G to F_1 can be calculated from the formula [see equation (3.2.3.96)]

$$n_F = [G : N_G(F_1)] = |G| : |N_G(F_1)|.$$
 (3.4.2.36)

The product of n_F and d_F is equal to the number n of ferroic domain states,

$$n = n_F d_F. (3.4.2.37)$$

The normalizer $N_G(F_1)$ enables one not only to determine which domain states have the symmetry F_1 but also to calculate all subgroups that are conjugate under G to F_1 (see Examples 3.2.3.22, 3.2.3.29 and 3.2.3.34 in Section 3.2.3.3).

Normalizers $N_G(F_1)$ and the number d_F of principal domain states with the same symmetry are given in Table 3.4.2.7 for all symmetry descents $G \supset F_1$. The number n_F of subgroups conjugate to F_1 is given by $n_F = n : d_F$.

All these results obtained for point-group symmetry descents can be easily generalized to microscopic domain states and space-group symmetry descents (see Section 3.4.2.5).

3.4.2.3. Property tensors associated with ferroic domain states

In the preceding section we derived relations for domain states without considering their specific physical properties. Basic formulae for the number of principal and secondary domain states [see equations (3.4.2.11) and (3.4.2.17), respectively] and the transformation properties of these domain states [equations (3.4.2.12) and (3.4.2.21), respectively] follow immediately from the symmetry groups G, F_1 of the parent and ferroic phases, respectively. Now we shall examine which components of property tensors specify principal and secondary domain states and how these tensor components change in different domain states.

A property tensor τ is specified by its components. The number $m_i(\tau)$ of independent tensor components of a certain tensor τ depends on the point-group symmetry G of the crystal (see Chapter 1.1). The number $m_c(\tau)$ of nonzero Cartesian (rectangular) components depends on the orientation of the crystal in the reference Cartesian coordinate system and is equal to, or greater than, the number $m_i(\tau)$ of independent tensor components; this number $m_i(\tau)$ is independent of orientation. Then there are $m_c(\tau) - m_i(\tau)$ linear relations between Cartesian tensor components. The difference $m_c(\tau) - m_i(\tau)$ is minimal for a 'standard' orientation, in which symmetry axes of the crystal are, if possible, parallel to the axes of the reference coordinate system for more on this choice, see Nye (1985) Appendix B, Sirotin & Shaskolskaya (1982), Shuvalov (1988) and IEEE Standards on Piezoelectricity (1987)]. Even in this standard orientation, only for point groups of triclinic, monoclinic and orthorhombic crystal systems is the number $m_c(\tau)$ of nonzero Cartesian components of each property tensor equal to the number $m_i(\tau)$ of independent tensor components, i.e. all Cartesian tensor components are independent. For all other point groups $m_c(\tau) - m_i(\tau) > 0$, i.e. there are always relations between some Cartesian tensor components. One can verify this statement for the strain tensor in Table 3.4.2.2.

The relations between Cartesian tensor components can be removed when one uses *covariant tensor components*. [Kopský (1979); see also the manual of the the software $GI \star KoBo$ -1 and Kopský (2001). An analogous decomposition of Cartesian tensors into irreducible parts has been performed by Jerphagnon *et al.* (1978).] Covariant tensor components are linear combinations of Cartesian tensor components that transform according to irreducible matrix representations $D^{(\alpha)}(G)$ of the group G of the crystal (*i.e.* they form a basis of irreducible representations of G; see Chapter 1.2). The number of covariant tensor

components equals the number of independent components of the tensor τ .

The advantage of expressing property tensors by covariant tensor components becomes obvious when one considers a change of a property tensor at a ferroic phase transition. A symmetry descent $G \supset F_1$ is accompanied by the preservation of, or an increase of, the number of independent Cartesian tensor components. The latter possibility can manifest itself either by the appearance of morphic Cartesian tensor components in the lowsymmetry phase or by such changes of nonzero Cartesian components that break some relations between tensor components in the high-symmetry phase. This is seen in our illustrative example of the strain tensor u. In the high-symmetry phase with $G = 4_z/m_z m_x m_{xy}$, the strain tensor has two independent components and three nonzero components: $u_{11} \neq u_{22} = u_{33}$. In the low-symmetry phase with $F_1 = 2_x m_y m_z$, there are three independent and three nonzero components: $u_{11} \neq u_{22} \neq u_{33}$, i.e. the equation $u_{22} = u_{33}$ does not hold in the parent phase. This change cannot be expressed by a single Cartesian morphic component.

Since there are no relations between covariant tensor components, any change of tensor components at a symmetry descent can be expressed by morphic covariant tensor components, which are zero in the parent phase and nonzero in the ferroic phase. In our example, the covariant tensor component of the spontaneous strain is $u_{11} - u_{22}$, which is a morphic component since $u_{11} - u_{22} = 0$ for the symmetry $4_z/m_z m_x m_{xy}$ but $u_{11} - u_{22} \neq 0$ for symmetry $2_x m_y m_z$.

Tensorial covariants are defined in an exact way in the manual of the software $GI\star KoBo$ -1 and in Kopský (2001). Here we give only a brief account of this notion. Consider a crystal with symmetry G and a property tensor τ with n_{τ} independent tensor components. Let $D^{(\alpha)}(G)$ be a d_{α} -dimensional physically irreducible matrix representation of G. The $D_a^{(\alpha)}(G)$ covariant of τ consists of the following d_{α} covariant tensor components: $\tau_{\alpha}^{\alpha} = (\tau_{a,1}^{\alpha}, \tau_{a,2}^{\alpha}, \ldots, \tau_{a,d_{\alpha}}^{\alpha})$, where $a = 1, 2, \ldots$ and $m = n_{\tau}/d_{\alpha}$ numbers different d_{α} -tuples formed from n_{τ} components of τ . These covariant tensor components are linear combinations of Cartesian components of τ that transform as so-called typical variables of the matrix representation $D^{(\alpha)}(G)$, i.e. the transformation properties under operations $g \in G$ of covariant tensor components are expressed by matrices $D^{\alpha}(g)$.

The relation between two presentations of the tensor τ is provided by *conversion equations*, which express Cartesian tensor components as linear combinations of covariant tensor components and *vice versa* [for details see the manual and Appendix E of the software GI*KoBo-1 and Kopský (2001)].

Tensorial covariants for all non-equivalent physically irreducible matrix representations of crystallographic point groups and all important property tensors up to rank four are listed in the software $GI \star KoBo$ -1 and in Kopský (2001). Thus, for example, in Table D of the software $GI \star KoBo$ -1, or in Kopský (2001) p. 5, one finds for the two-dimensional irreducible representation E of group 422 the following tensorial covariants: (P_1, P_2) , (d_{11}, d_{22}) , (d_{12}, d_{21}) , (d_{13}, d_{23}) , (d_{26}, d_{16}) , (d_{35}, d_{34}) .

Let us denote by $\tau_a^{(\alpha)(1)}$ a tensorial covariant of τ in the first single-domain state \mathbf{S}_1 . A crucial role in the analysis is played by the stabilizer $I_G(\tau_a^{(\alpha)(1)})$ of these covariants, *i.e.* all operations of the parent group G that leave $\tau_a^{(\alpha)(1)}$ invariant. There are three possible cases:

(1) If

$$I_G(\tau_a^{(\alpha)(1)}) = G,$$
 (3.4.2.38)

then all components of $\tau_a^{(\alpha)(1)}$ that are nonzero in the parent phase are also nonzero in the ferroic phase. All these components are the same in all principal domain states. For important property tensors and for all point groups G, these covariant tensor components are listed in the main tables of the software

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GI∗*KoBo*-1 and in Kopský (2001). The corresponding Cartesian tensor components are available in Section 1.1.4 and in standard textbooks (*e.g.* Nye, 1985; Sirotin & Shaskolskaya, 1982).

(2) If

$$I_G(\tau_a^{(\alpha)(1)}) = F_1,$$
 (3.4.2.39)

then any of $m=n_\tau/d_\alpha$ tensorial covariants $\tau_a^{(\alpha)}, a=1,2,\ldots,m$, is a possible principal tensor parameter $\varphi^{(1)}$ of the transition $G\supset F_1$. Any two of $n_f=|G|:|F_1|$ principal domain states differ in some, or all, components of these covariants. The principal tensor parameter φ plays a similar symmetric (but generally not thermodynamic) role as the order parameter η does in the Landau theory. Only for equitranslational phase transitions is one of the principal tensor parameters (that with the temperature-dependent coefficient) identical with the primary order parameter of the Landau theory (see Section 3.1.3).

(3) If

$$I_G(\tau_a^{(\alpha)(1)}) = L_1, \quad F_1 \subset L_1 \subset G,$$
 (3.4.2.40)

then $\tau_a^{(\alpha)(1)}$ represents the secondary tensor parameter λ (see Section 3.1.3.2). There exist $n_{\lambda} = |G| : |L_1|$ secondary domain states \mathbf{R}_1 , \mathbf{R}_2 , ..., $\mathbf{R}_{n_{\lambda}}$ that differ in λ . Unlike in the two preceding cases (1) and (2), several intermediate groups L_1, M_2, \ldots (with secondary tensor parameters λ, μ, \ldots) that fulfil condition (3.4.2.40) can exist.

Now we shall indicate how one can find particular property tensors that fulfil conditions (3.4.2.39) or (3.4.2.40). The solution of this group-theoretical task consists of three steps:

- (i) For a given point-group symmetry descent $G \supset F_1$, or $G \supset L_1$, one finds the *representation* Γ_η that specifies the *transformation properties of the principal, or secondary, tensor parameter*, which plays the role of the order parameters in a continuum description. This task is called an inverse Landau problem (see Section 3.1.3 for more details). The solution of this problem is available in Tables 3.4.2.7 and 3.1.3.1, in the software $GI\star KoBo$ -1 and in Kopský (2001), where the letters A, B signify one-dimensional irreducible representations, and letters E and E two- and three-dimensional ones. The dimensionality e0, or e1, of the representation e2, or e3, specifies the maximal number of independent components of the principal, or secondary, tensor parameter e4, or e5, respectively. 'Reducible' indicates that e7 is a reducible representation.
- (ii) In Table 3.1.3.1 one finds in the second column, for a given G and Γ_{η} , or Γ_{λ} (first column), the *standard variables* designating in a standardized way the covariant tensor components of the principal, or secondary, tensor parameters (for more details see Section 3.1.3.1 and the manual of the software $GI\star KoBo$ -1). For two- and three-dimensional irreducible representations, this column contains relations that restrict the values of the components and thus reduce the number of independent components.
- (iii) The association of covariant tensor components of property tensors with standard variables is tabulated for all irreducible representations in an abridged version in Table 3.1.3.1, in the

column headed *Principal tensor parameters*, and in full in the main table of the software *GI*KoBo-1* and of Kopský (2001).

Phase transitions associated with reducible representations are treated in detail only in the software *GI*KoBo-1* and in Kopský (2001). Fortunately, these phase transitions occur rarely in nature

A rich variety of observed structural phase transitions can be found in Tomaszewski (1992). This database lists 3446 phase transitions in 2242 crystalline materials.

Example 3.4.2.4. Morphic tensor components associated with $4_z/m_z m_{xy} \supset 2_x m_y m_z$ symmetry descent

- (1) Principal tensor parameters $\varphi^{(1)}$. The representation Γ_{η} that specifies the transformation properties of the principal tensor parameter $\varphi^{(1)}$ (and for equitranslational phase transitions also the primary order parameter $\eta^{(1)}$) can be found in the first column of Table 3.1.3.1 for $G=4_z/m_zm_xm_{xy}$ and $F_1=2_xm_ym_z$; the R-irreducible representation (R-irep) $\Gamma_{\eta}=E_u$. Therefore, the principal tensor parameter $\varphi^{(1)}$ (or the primary order parameter $\eta^{(1)}$) has two components $(\varphi_1^{(1)},\varphi_2^{(1)})$ [or $(\eta_1^{(1)},\eta_2^{(1)})$]. The standard variables are in the second column: $(\mathbf{x}_1^-,0)$. This means that only the first component $\varphi_1^{(1)}$ (or $\eta_1^{(1)}$) is nonzero. In the column Principal tensor parameters, one finds that $\varphi_1^{(1)}=P_1$ (or $\eta_1^{(1)}=P_1$), i.e. one principal tensor parameter is spontaneous polarization and the spontaneous polarization in the first domain state \mathbf{S}_1 is $P_{(s)}=(P,00)$. Other principal tensor parameters can be found in the software $GI\star KoBo$ -1 or in Kopský (2001), p. 185: $(g_4,0), (d_{11},0), (d_{12},0), (d_{13},0), (d_{26},0), (d_{35},0)$ (the physical meaning of the components is explained in Table 3.4.3.5).
 - (2) Secondary tensor parameters $\lambda^{(1)}, \mu^{(1)}, \ldots$

In the group lattice (group–subgroup chains) in Fig. 3.1.3.1, one finds that the only intermediate group between $4_z/m_zm_xm_{xy}$ and $2_xm_ym_z$ is $L_1=m_xm_ym_z$. In the same table of the software $GI\star KoBo$ -1 or in Kopský (2001), one finds $\Gamma_\lambda=B_{1g}$ and the following one-dimensional secondary tensor parameters: u_1-u_2 ; $A_{14}+A_{25}, A_{36}; s_{11}-s_{22}, s_{13}-s_{23}, s_{44}-s_{55}; Q_{11}-Q_{22}, Q_{12}-Q_{21}, Q_{13}-Q_{23}, Q_{31}-Q_{32}, Q_{44}-Q_{55}$.

The use of covariant tensor components has two practical advantages:

Firstly, the change of tensor components at a ferroic phase transition is completely described by the appearance of new nonzero covariant tensor components. If needed, Cartesian tensor components corresponding to covariant components can be calculated by means of *conversion equations*, which express Cartesian tensor components as linear combinations of covariant tensor components [for details on tensor covariants and conversion equations see the manual and Appendix E of the software *GI*KoBo-1* and Kopský (2001)].

Secondly, calculation of property tensors in various domain states is substantially simplified: transformations of Cartesian tensor components, which are rather involved for higher-rank tensors, are replaced by a simpler transformation of covariant tensor components by matrices $D^{(\eta)}$ of the matrix representation of Γ_{η} , or of Γ_{λ} [see again the software GI*KoBo-1 and Kopský

Table 3.4.2.4. Morphic properties, tensor parameters, order parameters and domain states

T, U, S, V: property tensors; TOP: designation of tensor or order parameter; Γ : representation of G expressing the transformation properties of TOP. The terms 'full' and 'partial' were introduced by Aizu (1970a).

Morphic property	TOP	Γ	Stabilizer of TOP	Domain states		
Spontaneous components of tensor T	φ	Γ_{φ}	F_1	Principal (full) in tensor T		
Spontaneous components of tensor U	ψ	Γ_{φ}	F_1	Principal (full) in tensor U		
Spontaneous components of tensor S	σ	Γ_{σ}	F_1	Principal (full) in tensor S		
Spontaneous components of tensor V	λ	Γ_{λ}	$L_1, F_1 \subset L_1 \subset G$	Degenerate (partial) in tensor V		
Primary order parameter	η	Γ_{η}	\mathcal{F}_1	Basic (microscopic)		
Pseudoproper order parameter	ζ	Γ_{η}	\mathcal{F}_1	Basic (microscopic)		
Secondary (improper) order parameter	ξ	Γ_{ξ}	$\mathcal{L}_1, \mathcal{F}_1 \subset \mathcal{L}_1 \subset \mathcal{G}$	Secondary (improper) microscopic		

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(2001)]. The determination of the tensor properties of all domain states is discussed in full in the book by Kopský (1982).

The relations between morphic properties, tensor parameters, order parameters and names of domain states are summarized in Table 3.4.2.4. Macroscopic principal domain states can be distinguished by various property tensors that transform either according to the same representation Γ_{φ} (tensors T and U) or different representations Γ_{φ} and Γ_{σ} (tensors T and S). In the microscopic description, a basic domain state may sometimes be shared by two physically different order parameters: a primary order parameter η (the order parameter, components of which form a quadratic invariant with a temperature-dependent coefficient in the free energy) and a pseudoproper order parameter ζ that transforms according to the same representation Γ_{η} as the primary order parameter but has a temperature coefficient that is almost independent of temperature. This is, however, rather rare (see, e.g., Tolédano & Dmitriev, 1996).

3.4.2.4. Synoptic table of ferroic transitions and domain states

The considerations of this and all following sections can be applied to any phase transition with point-group symmetry descent $G \supset F$. All such non-magnetic *crystallographically non-equivalent symmetry descents* are listed in Table 3.4.2.7 together with some other data associated with symmetry reduction at a ferroic phase transition. These symmetry descents can also be traced in lattices of subgroups of crystallographic point groups, which are displayed in Figs. 3.1.3.1 and 3.1.3.2.

The symmetry descents $G \supset F_1$ listed in Table 3.4.2.7 are analogous to Aizu's 'species' (Aizu, 1970a), in which the symbol F stands for the symbol \supset in our symmetry descent, and the orientation of symmetry elements of the group F_1 with respect to G is specified by letters p, s, ps, pp etc. A list of 212 non-ferro-

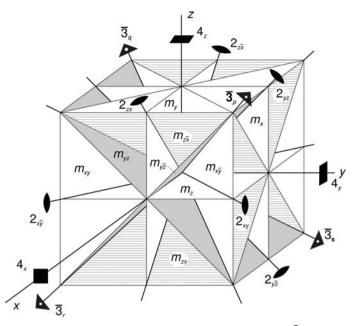


Fig. 3.4.2.3. Oriented symmetry operations of the cubic group $m\bar{3}m$ and of its subgroups. The Cartesian (rectangular) coordinate system x,y,z is identical with the crystallographic and crystallophysical coordinate systems. Correlation with other notations is given in Table 3.4.2.5.

magnetic species together with their property tensors is available online (Janovec, 2012).

As we have already stated, any systematic analysis of domain structures requires an unambiguous specification of the orientation and location of symmetry elements in space. Moreover, in a continuum approach, the description of crystal properties is performed in a rectangular (Cartesian) coordinate system, which

Table 3.4.2.5. Symbols of symmetry operations of the point group $m\bar{3}m$

Standard: symbols used in Section 3.1.3, in the present chapter and in the software; all symbols refer to the cubic crystallographic (Cartesian) basis, $p \equiv [111]$ (all positive), $q \equiv [\bar{1}1\bar{1}]$, $s \equiv [\bar{1}1\bar{1}]$, $s \equiv [\bar{1}1\bar{1}]$. BC: Bradley & Cracknell (1972). AH: Altmann & Herzig (1994). IT A: IT A (2005). Jones: Jones' faithful representation symbols express the action of a symmetry operation on a vector (xyz) (see e.g. Bradley & Cracknell, 1972).

Standard	BC	AH	IT A	Jones	Standard	ВС	AH	IT A	Jones
1 or <i>e</i>	E	E	1	x, y, z	$\bar{1}$ or i	I	i	$\bar{1}$ 0, 0, 0	$\bar{x}, \bar{y}, \bar{z}$
2_z	C_{2z}	C_{2z}	2 0, 0, z	\bar{x}, \bar{y}, z	m_z	σ_z	σ_z	m x, y, 0	x, y, \bar{z}
2_x	C_{2x}	C_{2x}	2 x, 0, 0	x, \bar{y}, \bar{z}	$m_{_{X}}$	σ_x	σ_{x}	m = 0, y, z	\bar{x}, y, z
2_y	C_{2y}	C_{2y}	2 0, y, 0	\bar{x}, y, \bar{z}	m_y	σ_y	σ_y	m x, 0, z	x, \bar{y}, z
2_{xy}	C_{2a}	C'_{2a}	2 x, x, 0	y, x, \bar{z}	m_{xy}	σ_{da}	σ_{d1}	$m \ x, \bar{x}, z$	\bar{y}, \bar{x}, z
$2_{x\bar{y}}$	C_{2b}	C'_{2b}	$2 x, \bar{x}, 0$	$\bar{y}, \bar{x}, \bar{z}$	$m_{xar{y}}$	σ_{db}	σ_{d2}	m x, x, z	y, x, z
2_{zx}	C_{2c}	C_{2c}'	2 x, 0, x,	z, \bar{y}, x	m_{zx}	σ_{dc}	σ_{d3}	$m \ \bar{x}, y, x,$	\bar{z}, y, \bar{x}
$2_{z\bar{x}}$	C_{2e}	C'_{2e}	$2 \bar{x}, 0, x$	$\bar{z}, \bar{y}, \bar{x}$	$m_{z\bar{x}}$	σ_{de}	σ_{d5}	m x, y, x	z, y, x
2_{yz}	C_{2d}	C'_{2d}	2 0, y, y	\bar{x}, z, y	m_{yz}	σ_{dd}	σ_{d4}	$m \ x, y, \bar{y}$	x, \bar{z}, \bar{y}
$2_{y\bar{z}}$	C_{2f}	C'_{2f}	$2 0, y, \bar{y}$	$\bar{x}, \bar{z}, \bar{y}$	$m_{y\bar{z}}$	σ_{df}	σ_{d6}	m x, y, y	x, z, y
3_p	C_{31}^{+}	C_{31}^{+}	$3^+ x, x, x$	z, x, y	$\bar{3}_p$	S_{61}^{-}	S_{61}^{-}	$\bar{3}^+$ x, x, x	$\bar{z}, \bar{x}, \bar{y}$
3_q	C_{32}^{+}	C_{32}^{+}	3^+ \bar{x}, \bar{x}, x	\bar{z}, x, \bar{y}	$\bar{3}_q$	S_{62}^{-}	S_{62}^{-}	$\bar{3}^+$ \bar{x}, \bar{x}, x	z, \bar{x}, y
3_r	C_{33}^{+}	C_{33}^{+}	3^+ x, \bar{x}, \bar{x}	\bar{z}, \bar{x}, y	$\bar{3}_r$	S_{63}^{-}	S_{63}^{-}	$\bar{3}^+$ x, \bar{x}, \bar{x}	z, x, \bar{y}
3_s	C_{34}^{+}	C_{34}^{+}	3^+ \bar{x}, x, \bar{x}	z, \bar{x}, \bar{y}	$\bar{3}_s$	S_{64}^{-}	S_{64}^{-}	$\bar{3}^+$ \bar{x}, x, \bar{x}	\bar{z}, x, y
3_{p}^{2}	C_{31}^{-}	C_{31}^{-}	$3^- x, x, x$	y, z, x	$\bar{3}_{p}^{5}$	S_{61}^{+}	S_{61}^{+}	$\bar{3}^ x, x, x$	$\bar{y}, \bar{z}, \bar{x}$
3_q^2	C_{32}^{-}	C_{32}^{-}	$3^ \bar{x}, \bar{x}, x$	y, \bar{z}, \bar{x}	$\bar{3}_q^5$	S_{62}^{+}	S_{62}^{+}	$\bar{3}^ \bar{x}, \bar{x}, x$	\bar{y}, z, x
3_r^2	C_{33}^{-}	C_{33}^{-}	$3^ x, \bar{x}, \bar{x}$	\bar{y}, z, \bar{x}	$\bar{\mathfrak{Z}}_r^5$	S_{63}^{+}	S_{63}^{+}	$\bar{3}^ x, \bar{x}, \bar{x}$	y, \bar{z}, x
3_s^2	C_{34}^{-}	C_{34}^{-}	$3^ \bar{x}, x, \bar{x}$	\bar{y}, \bar{z}, x	$\bar{3}_s^5$	S_{64}^+	S_{64}^{+}	$\bar{3}^ \bar{x}, x, \bar{x}$	y, z, \bar{x}
4 _z	C_{4z}^+	C_{4z}^+	4^{+} 0, 0, z	\bar{y}, x, z	$\bar{4}_z$	S_{4z}^-	S_{4z}^-	$\bar{4}^+$ 0, 0, z	y, \bar{x}, \bar{z}
4 _x	C_{4x}^+	C_{4x}^+	$4^+ x, 0, 0$	x, \bar{z}, y	$\bar{4}_x$	S_{4x}^-	S_{4x}^-	$\bar{4}^+ x, 0, 0$	\bar{x}, z, \bar{y}
4 _y	C_{4y}^+	C_{4y}^+	4^+ 0, y , 0	z, y, \bar{x}	$\bar{4}_y$	S_{4y}^-	S_{4y}^-	$\bar{4}^+$ 0, y, 0	\bar{z}, \bar{y}, x
4_z^3	C_{4z}^-	C_{4z}^-	4^{-} 0, 0, z	y, \bar{x}, z	$\bar{4}_z^3$	S_{4z}^+	S_{4z}^+	$\bar{4}^- 0, 0, z$	\bar{y}, x, \bar{z}
4_x^3	C_{4x}^-	C_{4x}^-	$4^- x, 0, 0$	x, z, \bar{y}	$\bar{4}_x^3$	S_{4x}^+	S_{4x}^+	$\bar{4}^- x, 0, 0$	\bar{x}, \bar{z}, y
4_y^3	C_{4y}^-	C_{4y}^-	4^{-} 0, y, 0	\bar{z}, y, x	$\bar{4}_y^3$	S_{4y}^+	S_{4y}^+	$\bar{4}^- 0, y, 0$	z, \bar{y}, \bar{x}

495 references