

## 2.1. INTRODUCTION TO BASIC CRYSTALLOGRAPHY

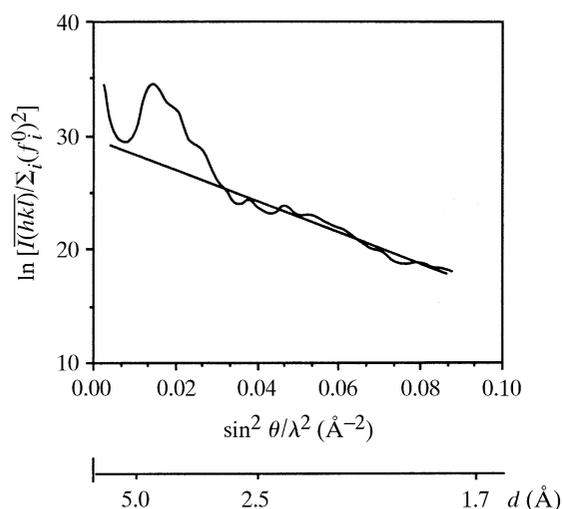


Fig. 2.1.4.10. The Wilson plot for phospholipase  $A_2$  with data to 1.7 Å resolution. Only beyond 3 Å resolution is it possible to fit the curve to a straight line. Reproduced with permission from Drenth (1999). Copyright (1999) Springer-Verlag.

$$\overline{I(\mathbf{S})} = K \overline{I(\text{abs.}, \mathbf{S})} = K \exp(-2B \sin^2 \theta / \lambda^2) \sum_i (f_i^o)^2. \quad (2.1.4.12)$$

To determine  $K$  and  $B$ , equation (2.1.4.11) is written in the form

$$\ln[\overline{I(\mathbf{S})} / \sum_i (f_i^o)^2] = \ln K - 2B \sin^2 \theta / \lambda^2. \quad (2.1.4.13)$$

Because  $f_i^o$  depends on  $\sin \theta / \lambda$ , average intensities,  $\overline{I(\mathbf{S})}$ , are calculated for shells of narrow  $\sin \theta / \lambda$  ranges.  $\ln[\overline{I(\mathbf{S})} / \sum_i (f_i^o)^2]$  is plotted against  $\sin^2 \theta / \lambda^2$ . The result should be a straight line with slope  $-2B$ , intersecting the vertical axis at  $\ln K$  (Fig. 2.1.4.10).

For proteins, the Wilson plot gives rather poor results because the assumption in deriving equation (2.1.4.11) that the angles,  $[2\pi(\mathbf{r}_i - \mathbf{r}_j) \cdot \mathbf{S}]$ , are evenly distributed over the range  $0-2\pi$  for  $i \neq j$  is not quite valid, especially not in the  $\sin \theta / \lambda$  ranges at low resolution.

As discussed above, the average value of the structure factors,  $\overline{F(\mathbf{S})}$ , decreases with the scattering angle because of two effects:

- (1) the decrease in the atomic scattering factor  $f$ ;
- (2) the temperature factor.

This decrease is disturbing for statistical studies of structure-factor amplitudes. It is then an advantage to eliminate these effects by working with normalized structure factors,  $E(\mathbf{S})$ , defined by

$$E(\mathbf{S}) = F(\mathbf{S}) / \left( \sum_j f_j^2 \right)^{1/2} \\ = F(\mathbf{S}) \exp(B \sin^2 \theta / \lambda^2) / \left[ \sum_j (f_j^o)^2 \right]^{1/2}. \quad (2.1.4.14)$$

The application of equation (2.1.4.14) to  $|\overline{E(\mathbf{S})}|^2$  gives

$$|\overline{E(\mathbf{S})}|^2 = \overline{|F(\mathbf{S})|^2} / \sum_j f_j^2 = \overline{|F(\mathbf{S})|^2} / \overline{|F(\mathbf{S})|^2} = 1. \quad (2.1.4.15)$$

The average value,  $|\overline{E(\mathbf{S})}|^2$ , is equal to 1. The advantage of working with normalized structure factors is that the scaling is not important, because if equation (2.1.4.14) is written as

$$E(\mathbf{S}) = \frac{F(\mathbf{S})}{(|F(\mathbf{S})|^2)^{1/2}},$$

a scale factor affects numerator and denominator equally.

In practice, the normalized structure factors are derived from the observed data as follows:

$$E(\mathbf{S}) = F(\mathbf{S}) \exp(B \sin^2 \theta / \lambda^2) / (\varepsilon |F(\mathbf{S})|^2)^{1/2}, \quad (2.1.4.16)$$

where  $\varepsilon$  is a correction factor for space-group symmetry. For general reflections it is 1, but it is greater than 1 for reflections having  $\mathbf{h}$  parallel to a symmetry element. This can be understood as follows. For example, if  $m$  atoms are related by this symmetry element,  $\mathbf{r}_j \cdot \mathbf{S}$  (with  $j$  from 1 to  $m$ ) is the same in their contribution to the structure factor

$$F(\mathbf{h}) = \sum_{j=1}^m f_j \exp(2\pi i \mathbf{r}_j \cdot \mathbf{S}).$$

They act as one atom with scattering factor  $m \times f$  rather than as  $m$  different atoms, each with scattering factor  $f$ . According to equation (2.1.4.11), this increases  $F(\mathbf{h})$  by a factor  $m^{1/2}$  on average. To make the  $F$  values of all reflections statistically comparable,  $F(\mathbf{h})$  must be divided by  $m^{1/2}$ . For a detailed discussion, see *IT B* (2001), Chapter 2.1, by A. J. C. Wilson and U. Shmueli.

## 2.1.5. Reciprocal space and the Ewald sphere

A most convenient tool in X-ray crystallography is the reciprocal lattice. Unlike real or direct space, reciprocal space is imaginary. The reciprocal lattice is a superior instrument for constructing the X-ray diffraction pattern, and it will be introduced in the following way. Remember that vector  $\mathbf{S}(hkl)$  is perpendicular to a reflecting plane and has a length  $|\mathbf{S}(hkl)| = 2 \sin \theta / \lambda = 1/d(hkl)$  (Section 2.1.4.5). This will now be applied to the boundary planes of the unit cell: the  $bc$  plane or (100), the  $ac$  plane or (010) and the  $ab$  plane or (001).

For the  $bc$  plane or (100): indices  $h = 1, k = 0$  and  $l = 0$ ;  $\mathbf{S}(100)$  is normal to this plane and has a length  $1/d(100)$ . Vector  $\mathbf{S}(100)$  will be called  $\mathbf{a}^*$ .

For the  $ac$  plane or (010): indices  $h = 0, k = 1$  and  $l = 0$ ;  $\mathbf{S}(010)$  is normal to this plane and has a length  $1/d(010)$ . Vector  $\mathbf{S}(010)$  will be called  $\mathbf{b}^*$ .

For the  $ab$  plane or (001): indices  $h = 0, k = 0$  and  $l = 1$ ;  $\mathbf{S}(001)$  is normal to this plane and has a length  $1/d(001)$ . Vector  $\mathbf{S}(001)$  will be called  $\mathbf{c}^*$ .

From the definition of  $\mathbf{a}^*$ ,  $\mathbf{b}^*$  and  $\mathbf{c}^*$  and the Laue conditions [equation (2.1.4.7)], the following properties of the vectors  $\mathbf{a}^*$ ,  $\mathbf{b}^*$  and  $\mathbf{c}^*$  can be derived:

$$\mathbf{a}^* \cdot \mathbf{a} = \mathbf{a} \cdot \mathbf{a}^* = \mathbf{a} \cdot \mathbf{S}(100) = h = 1.$$

Similarly

$$\mathbf{b}^* \cdot \mathbf{b} = \mathbf{b} \cdot \mathbf{S}(010) = k = 1,$$

and

$$\mathbf{c}^* \cdot \mathbf{c} = \mathbf{c} \cdot \mathbf{S}(001) = l = 1.$$

However,  $\mathbf{a}^* \cdot \mathbf{b} = 0$  and  $\mathbf{a}^* \cdot \mathbf{c} = 0$  because  $\mathbf{a}^*$  is perpendicular to the (100) plane, which contains the  $b$  and  $c$  axes. Correspondingly,  $\mathbf{b}^* \cdot \mathbf{a} = \mathbf{b}^* \cdot \mathbf{c} = 0$  and  $\mathbf{c}^* \cdot \mathbf{a} = \mathbf{c}^* \cdot \mathbf{b} = 0$ .

Proposition: The endpoints of the vectors  $\mathbf{S}(hkl)$  form the points of a lattice constructed with the unit vectors  $\mathbf{a}^*$ ,  $\mathbf{b}^*$  and  $\mathbf{c}^*$ .

Proof: Vector  $\mathbf{S}$  can be split into its coordinates along the three directions  $\mathbf{a}^*$ ,  $\mathbf{b}^*$  and  $\mathbf{c}^*$ :

$$\mathbf{S} = X \cdot \mathbf{a}^* + Y \cdot \mathbf{b}^* + Z \cdot \mathbf{c}^*. \quad (2.1.5.1)$$

Our proposition is true if  $X$ ,  $Y$  and  $Z$  are whole numbers and indeed they are. Multiply equation (2.1.5.1) on the left and right side by  $\mathbf{a}$ .

